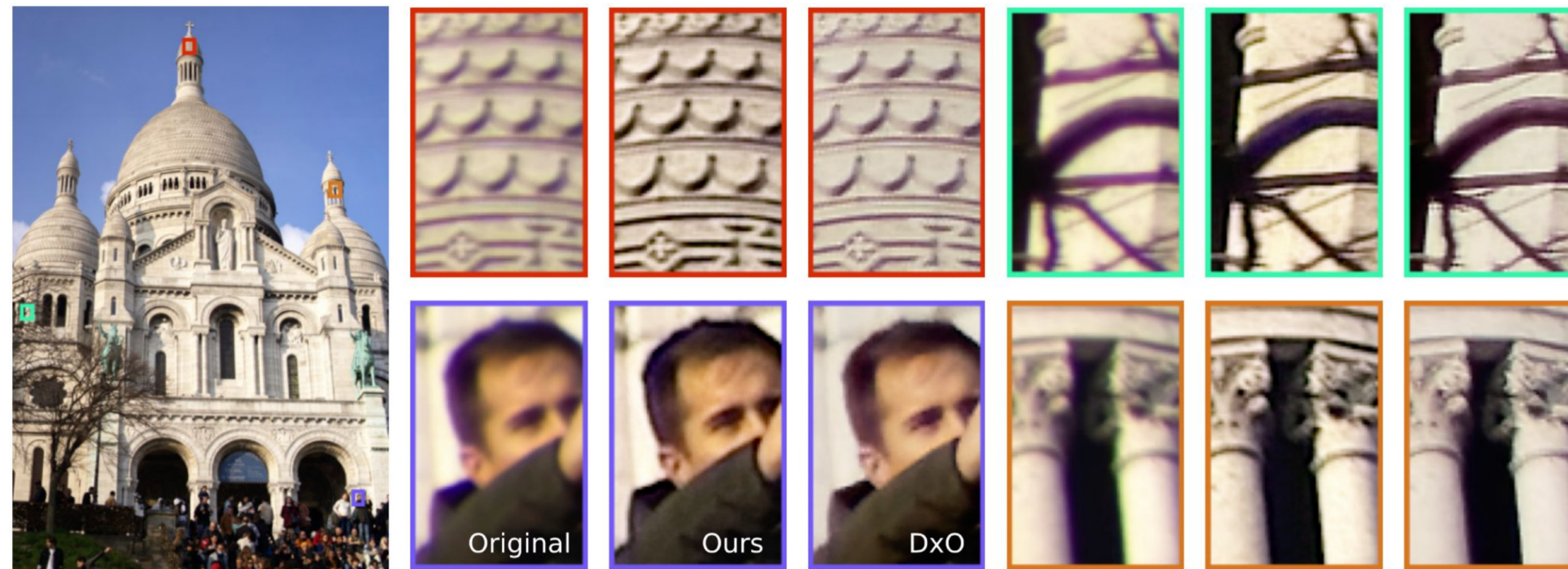
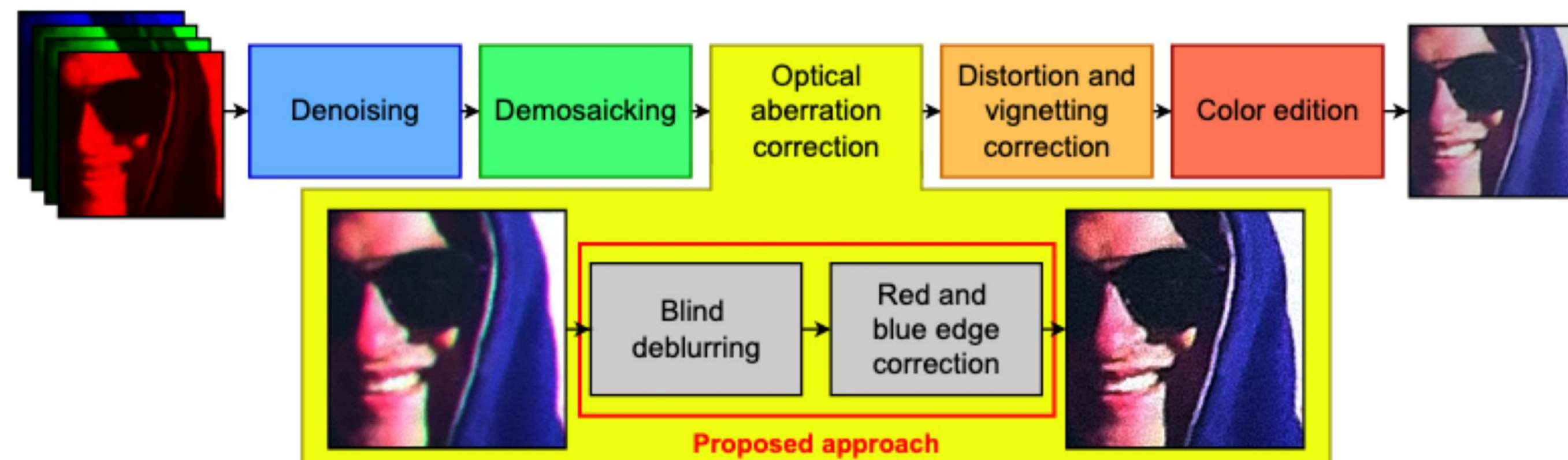


Problem statement



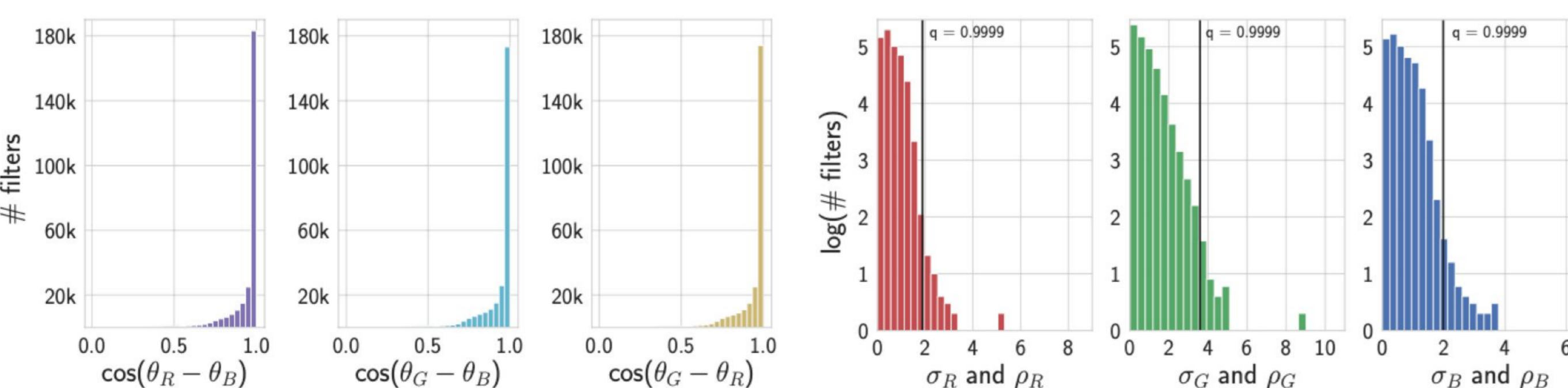
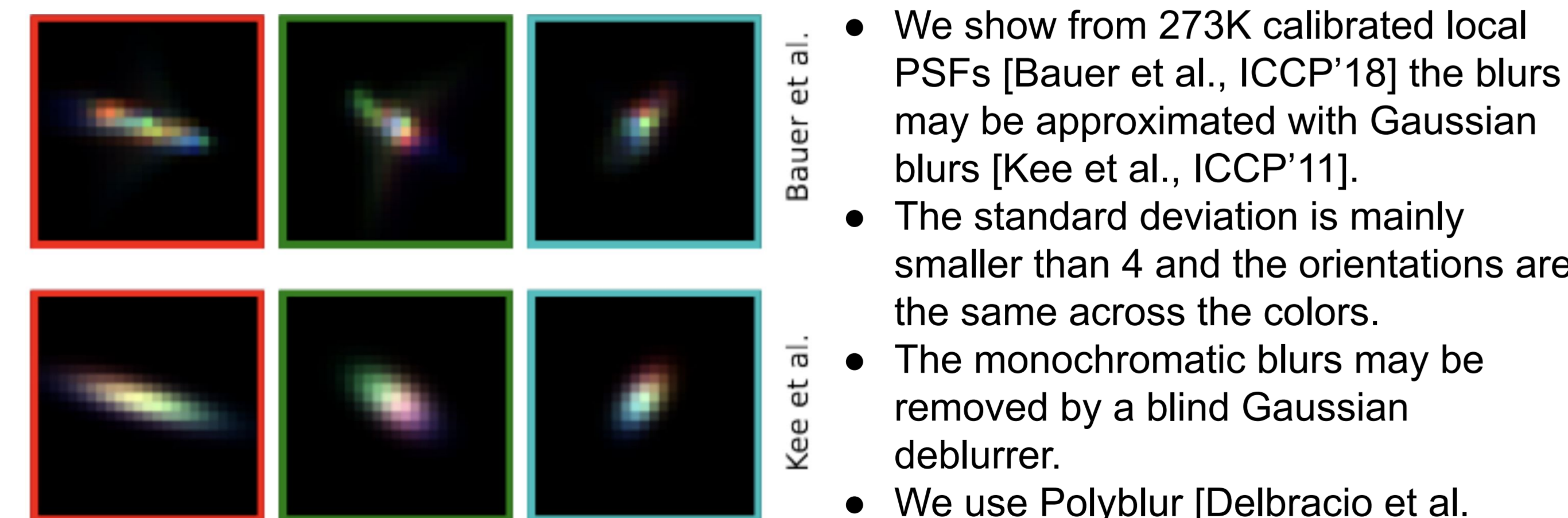
- The photographs are naturally degraded by optical aberration artifacts.
- Existing solutions (e.g., DxO PhotoLab) are **non-blind**: based on tedious calibration.
- We propose a fast **blind** method: give the image and press the button!

Proposed approach



- Optical aberration correction usually happens in the ISP pipeline, after denoising and demosaicking.
- After analysis of the aberration, we decompose them into blur and warp.
- We address these two issues in two separate steps:
 - **Blind Gaussian deblurring**: we remove simple small parametric blurs.
 - **Edge correction**: we correct the remaining red and blue shifted edges.

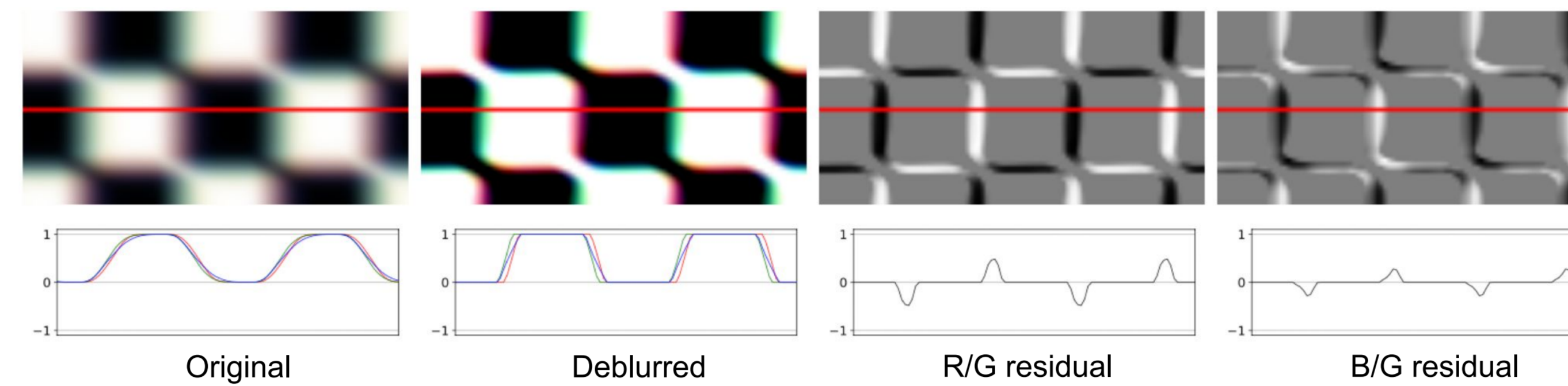
Gaussian blind deblurring



(a) Assumption on θ_c .

(b) Assumption on σ_c and ρ_c .

Red and blue edge correction

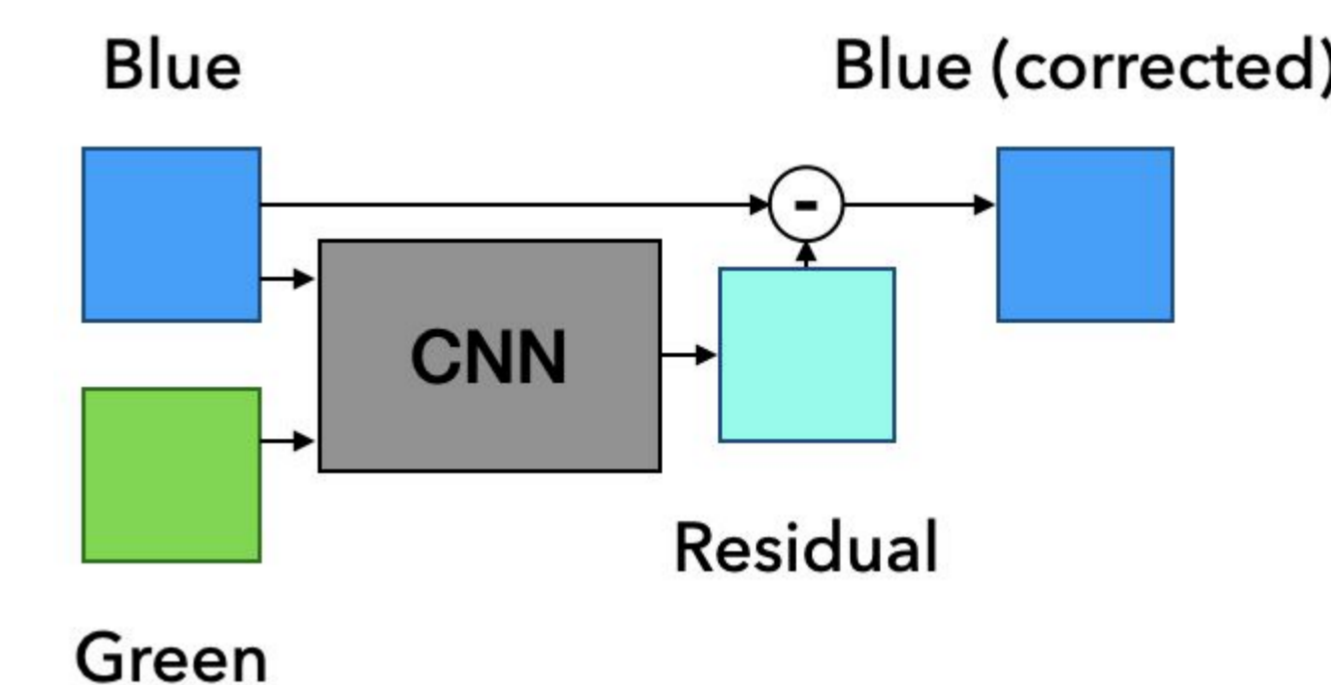


- The chromatic aberrations result in color fringes next to the salient edges.
- According to [Cheng et al., TIP'13] the red-green and blue-green color residuals are good detectors of the chromatic aberrations.
- Therefore, after deblurring, we correct the chromatic aberrations.
- We propose a CNN and a training loss tailored to correct color fringes.

CNN architecture

$$\hat{u}_c = z_c - \phi_\nu(z_c, z_G)$$

- We design a residual CNN.
- It takes as input two color channels.
- We take the green image as the reference and restore the red and blue channels.
- It predicts a red or blue residual to be subtracted to the red or blue input channel.



Training loss

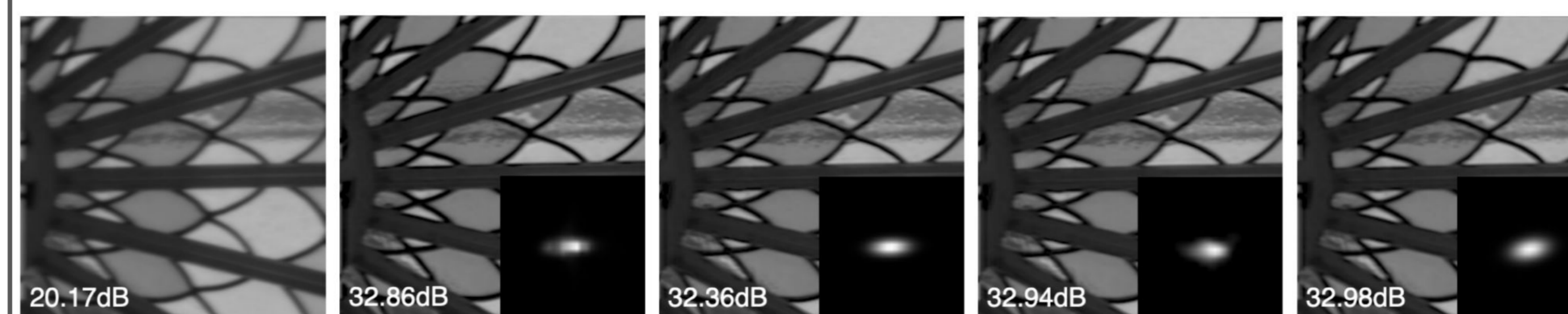
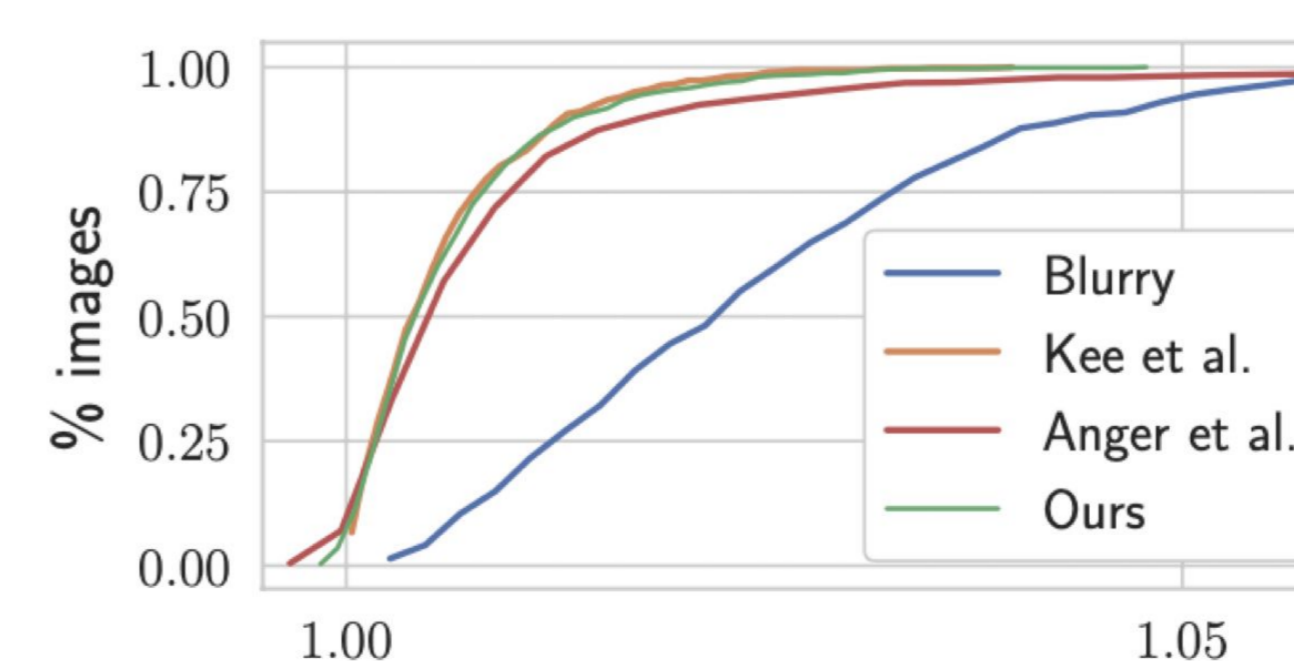
- A typical training loss compares the pixel colors of the images.
- We instead minimize the color residuals of the prediction and the target to favor **achromatic** edges.

$$\sum_{i=1}^N \sum_{c \in \{R, B\}} \left\| \left(u_c^{(i)} - u_G^{(i)} \right) - \left(z_c^{(i)} - \phi_\nu(z_c^{(i)}, z_G^{(i)}) - z_G^{(i)} \right) \right\|_1$$

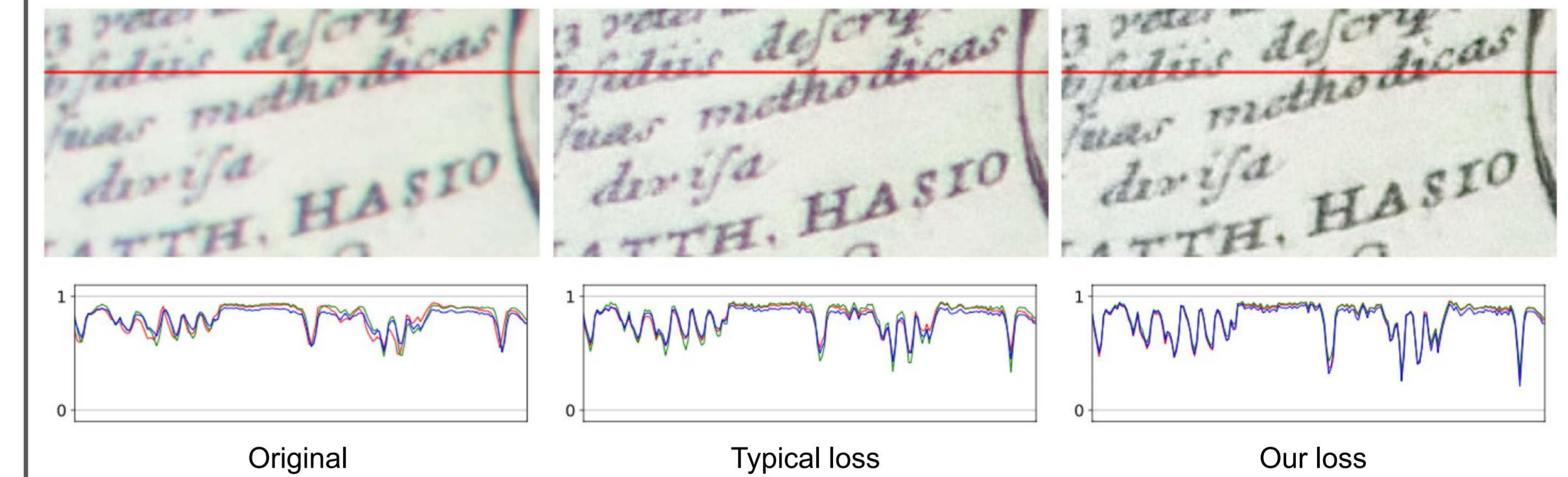
Validation of deblurring

- We validate the Gaussian blur assumption for local PSF correction.
- We compare our approach to parametric [Kee et al., ICCP'11] and non-parametric [Anger et al., IPOL'19] blind deblurring.
- We achieve similar results to Anger et al.'s and GT kernel inversions.
- We are much faster than Anger et al. while being as accurate.

$$R(\hat{g}_G, g_G) = \frac{\text{SSIM}[p(g_G) * v, u] + 2}{\text{SSIM}[p(\hat{g}_G) * v, u] + 2}$$

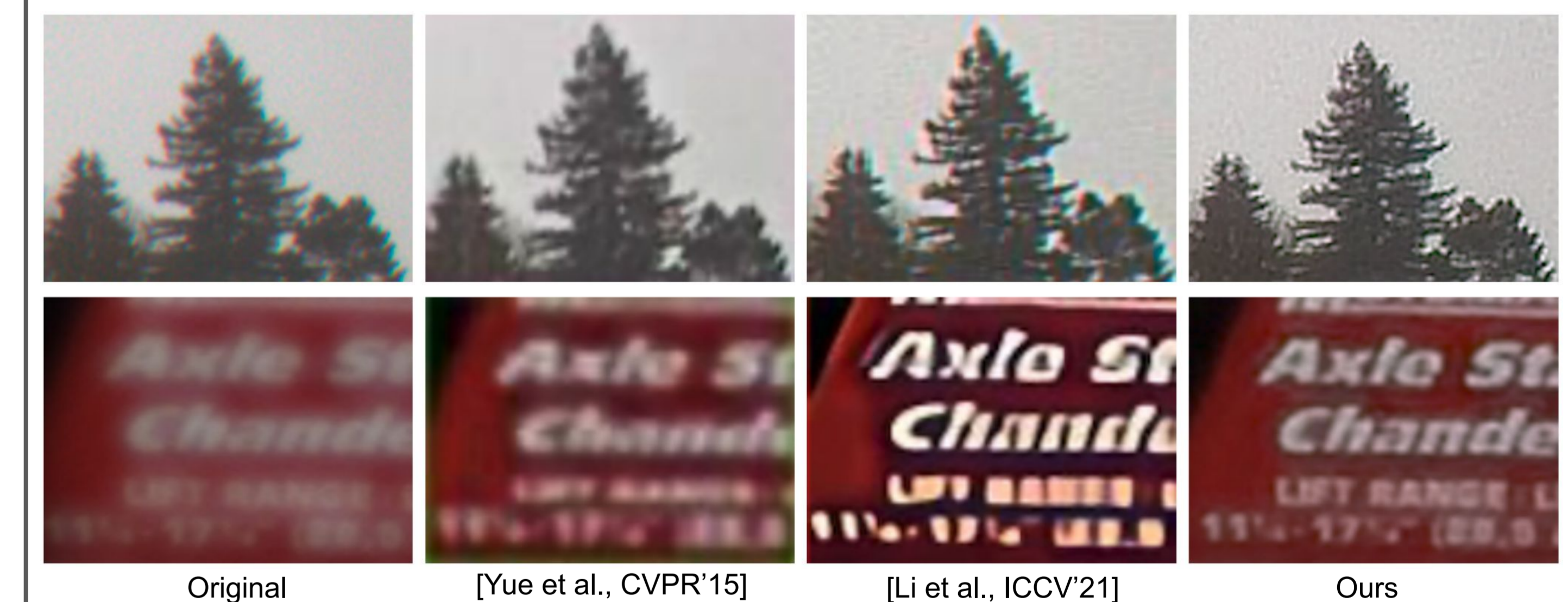


Impact of the training loss



- We trained two networks: with the typical image difference loss and our proposed residual difference loss.
- Predictions with the typical approach: the images show color tints next to the edges.
- Predictions with our approach: the images have salient edges that are much more achromatic.

Optical aberration removal results

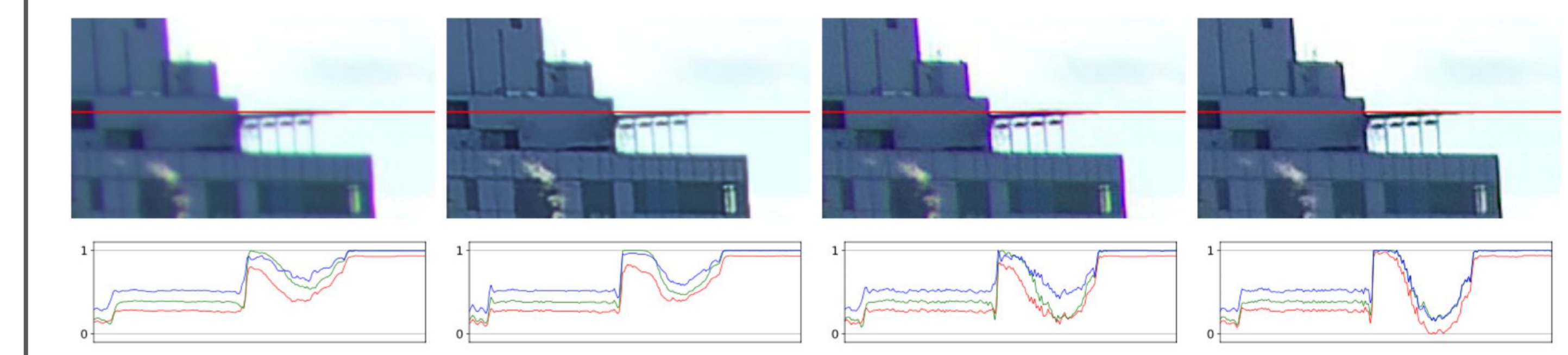


- Comparison with SOTA optimization and CNN optical aberration removal methods.
- We do much better while being faster than [Li et al., ICCV'21] by order of magnitudes.

Method	Time (s)	Flops	Params	Mem. (Gb)
[1]	29.1	27.3T	17.09M	8.9
Ours	1.7	33.1G	0.16M	2.4

Table 1. Speed and efficiency for a 6000 × 4000 image.

- In particular, we get rid of all the chromatic aberrations thanks to our edge filtering formulation.
- **Limitations**: we do not perfectly restore purple fringes (optical aberration + saturation) and blurs not captured by Gaussian blurs.



Conclusion

- We have presented a fast two-stage blind approach to optical aberration removal.
- We decompose the problem into blind Gaussian deblurring and defringing.
- We are much faster than the SOTA while being more accurate.
- Moving from the Gaussian blur model is left to future work.

Paper and code

